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1: #include <iostream>
2: #include <cmath>
3: using namespace std;
4:
5: double cube_root( double x )
6: {
7:     double y = pow( abs( x ), 1.0/3.0 );
8:     if ( x < 0 ) y = -y;
9:     return( y );
10: }
11:
12: int main()
13: {
14:     double a, b, c, d;
15:     double p, q, D, alpha, beta, theta;
16:     double a3, b3;
17:     double x1, x2, x3, y;
18:
19:     cout << "To find the solutions of ax^3+bx^2+cx+d=0" << "\n\n";
20:     cout << "Enter a, b, c, & d" << "\n";
21:     cout << "a = "; cin >> a;
22:     cout << "b = "; cin >> b;
23:     cout << "c = "; cin >> c;
24:     cout << "d = "; cin >> d;
25:     cout << "\n\n";
26:     if ( a == 0 ) {
27:         cout << "Your equation is not cubic!\n\n";
28:         return( 0 );
29:     }
30:     cout << "The solutions are:" << "\n";
31:
32:     p = ( 3*a*c - b*b ) / ( 9*a*a );
33:     q = ( 9*a*b*c - 2*b*b*b - 27*a*a*d ) / ( 54*a*a*a );
34:     D = pow( p, 3 ) + pow( q, 2 );
35:
36:     if ( D > 0 ) { // One real and two complex conjugates
37:         alpha = q + sqrt( D );
38:         beta = q - sqrt( D );
39:         a3 = cube_root( alpha );
40:         b3 = cube_root( beta );
41:         x1 = a3 + b3 - b / ( 3*a );
42:         x2 = -0.5 * ( a3 + b3 ) - b / ( 3*a ); // Real part of solution
43:         y = sqrt( 3.0 ) / 2 * ( a3 - b3 ); // Imaginary part of solution
44:         cout << "x1 = " << x1 << '\n';
45:         cout << "x2 = " << x2 << " + " << y << " i" << '\n';
46:         cout << "x3 = " << x2 << " - " << y << " i" << '\n';
47:     }
48:     else if ( D == 0 ) { // Three real (at least two are equal)
49:         alpha = q;
50:         beta = q;
51:         a3 = cube_root( alpha );
52:         b3 = cube_root( beta );
53:         x1 = a3 + b3 - b / ( 3*a );
54:         x2 = -0.5 * ( a3 + b3 ) - b / ( 3*a );
55:         cout << "x1 = " << x1 << '\n';

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56:         cout << "x2 = " << x2 << '\n';
57:         cout << "x3 = " << x2 << '\n';
58:     }
59:     else { // Three real
60:         theta = acos( q / sqrt( -p*p*p ) );
61:         x1 = 2 * sqrt( -p ) * cos( theta / 3.0 ) - b / ( 3*a );
62:         x2 = 2 * sqrt( -p ) * cos( theta / 3.0 + 2*M_PI / 3.0 ) - b / ( 3*a );
63:         x3 = 2 * sqrt( -p ) * cos( theta / 3.0 + 4*M_PI / 3.0 ) - b / ( 3*a );
64:         cout << "x1 = " << x1 << '\n';
65:         cout << "x2 = " << x2 << '\n';
66:         cout << "x3 = " << x3 << '\n';
67:     }
68:
69:     return( 0 );
70: }

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